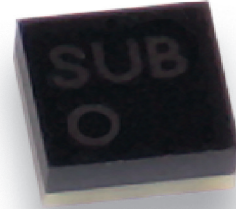


AFF756

MagnetoResistive Field Sensor



The AFF756 is a low noise magnetic field sensor based on the Anisotropic-MagnetoResistive (AMR) effect.

The sensor contains a Wheatstone bridge including a flip coil for offset correction. This measurement principle also reduces the temperature coefficient of the offset by a factor of 100.

The AFF756 is available as an LGA package (RoHS-conform) for SMD assembly.

Product Overview

Article description	Package	Delivery Type
AFF756AMA-AE	LGA8	Tape on reel

Quick Reference Guide

Symbol	Parameter	Min.	Typ.	Max.	Unit
V_{CC}	Supply voltage	1.2	5.0	9.0	V
R_B	Bridge resistance ¹⁾	0.7	1.0	1.3	k Ω
S	Sensitivity (in range ± 160 A/m)	8.0	10.0	12.0	$\frac{mV}{V}$ kA/m
I_F	Flip current (required)	± 400	-	-	mA
R_F	Flip coil resistance	-	1.5	2.0	Ω

¹⁾ Bridge resistance between pins 6 and 3; 5 and 2.

Absolute Maximum Ratings

In accordance with the absolute maximum rating system (IEC60134).

Symbol	Parameter	Min.	Max.	Unit
V_{CC}	Supply voltage	-20	+20	V
I_{Fmax}	Maximum flip current ²⁾	-1.0	+1.0	A
P_F	Maximum flip power dissipation	-	50	mW
T_{amb}	Ambient temperature	-40	+125	$^{\circ}C$
T_{stg}	Storage temperature	-40	+125	$^{\circ}C$
$V_{isolation}$	Voltage between bridge and flip coil	-200	+200	V

²⁾ 10 μs pulse, 400 μs pause.

Stresses beyond those listed under "Absolute maximum ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Features

- Based on the AnisotropicMagnetoResistive (AMR) effect
- Contains one Wheatstone Bridge
- Integrated flip coil
- Temperature range from $-40^{\circ}C$ to $+125^{\circ}C$

Advantages

- Extreme sensitivity
- Wide range of magnetic field strength
- Low power consumption
- Low flip coil resistance
- Very good signal to noise ratio

Applications

- Compass
- Electronic navigation systems
- Battery powered applications
- Magnetometry
- Measurement of terrestrial magnetic field
- Traffic detection



ESD

Magnetic Data

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
H_{ext}	Operating magnetic field range		-800	-	+800	A/m
B_{RES}	Resolution	$V_{\text{CC}} = 5 \text{ V}$; BW = 50 Hz	-	2.0	-	nT

Electrical Data of MR-Bridge

$T_{\text{amb}} = 25 \text{ }^\circ\text{C}$; $V_{\text{CC}} = 5 \text{ V}$; unless otherwise specified.

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
V_{CC}	Supply voltage		1.2	5.0	9.0	V
S	Sensitivity	In the operating range of $\pm 160 \text{ A/m}$	8.0	10.0	12.0	$\frac{\text{mV/V}}{\text{kA/m}}$
TC_S	Temperature coefficient of Sensitivity ¹⁾	See Fig. 5	-0.32	-0.36	-0.40	%/K
R_B	Bridge resistance ²⁾		0.7	1.0	1.3	k Ω
TC_{RB}	Temperature coefficient of R_B ³⁾		0.22	0.26	0.30	%/K
V_{off}	Offset voltage per V_{CC}		-1.0	-	+1.0	mV/V
$TC_{V_{\text{off}}}$	Temperature coefficient of V_{off} ⁴⁾		-1.0	-	+1.0	$\mu\text{V/V/K}$
H_{off}	Magnetic offset per V_{CC}		-	0.15	-	A/m/V
N	Noise level	$f > 100 \text{ Hz}$	-	10.0	20.0	nV/ $\sqrt{\text{Hz}}$
$\epsilon_{\text{Lin},80}$	Linearity error @ $\pm 160 \text{ A/m}$	$-160 \leq H_{\text{ext}} \leq +160 \text{ A/m}$	-	0.15	0.25	% of FS
$\epsilon_{\text{Lin},240}$	Linearity error @ $\pm 480 \text{ A/m}$	$-480 \leq H_{\text{ext}} \leq +480 \text{ A/m}$	-	0.80	0.90	% of FS
$\epsilon_{\text{Lin},400}$	Linearity error @ $\pm 800 \text{ A/m}$	$-800 \leq H_{\text{ext}} \leq +800 \text{ A/m}$	-	2.30	2.70	% of FS

$$1) \quad TC_S = 100 \cdot \frac{S_{(T_2)} - S_{(T_1)}}{S_{(T_1)} \cdot (T_2 - T_1)} \quad \text{with } T_1 = 25 \text{ }^\circ\text{C}; T_2 = 125 \text{ }^\circ\text{C}.$$

2) Bridge resistance between pins 2 and 5, 3 and 6.

$$3) \quad TC_{RB} = 100 \cdot \frac{R_{B(T_2)} - R_{B(T_1)}}{R_{B(T_1)} \cdot (T_2 - T_1)} \quad \text{with } T_1 = 25 \text{ }^\circ\text{C}; T_2 = 125 \text{ }^\circ\text{C}.$$

$$4) \quad TC_{V_{\text{off}}} = \frac{V_{\text{off}(T_2)} - V_{\text{off}(T_1)}}{T_2 - T_1} \quad \text{with } T_1 = 25 \text{ }^\circ\text{C}; T_2 = 125 \text{ }^\circ\text{C}.$$

Electrical Data of Flip Coil and Test Connectors

$T_{\text{amb}} = 25 \text{ }^\circ\text{C}$; $V_{\text{CC}} = 5 \text{ V}$; unless otherwise specified.

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
I_F	Flip current (required)	1 μs on, 1 ms off	± 400	-	-	mA
t_{IF}	Flip pulse duration		-	1.0	2.0	μs
I_{Fmax}	Flip current (maximum)	10 μs on, 400 μs off	-	-	± 1.0	A
R_F	Flip coil resistance		-	1.5	2.0	Ω
TC_{RF}	Temperature coefficient of R_F ⁵⁾		0.30	0.35	0.40	%/K

$$5) \quad TC_{RF} = 100 \cdot \frac{R_{F(T_2)} - R_{F(T_1)}}{R_{F(T_1)} \cdot (T_2 - T_1)} \quad \text{with } T_1 = 25 \text{ }^\circ\text{C}; T_2 = 125 \text{ }^\circ\text{C}.$$

Dynamic Data

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
f	Frequency range		1	-	-	MHz

AFF756 in LGA-Housing

Pinning

Pin	Symbol	Parameter
1	+I _F	Flip coil
2	-V _o	Negative output voltage
3	GND	Ground
4	N.C	Not connected
5	+V _o	Positive output voltage
6	V _{CC}	Supply voltage
7	-I _F	Flip coil
8	N.C	Not connected

Pin 1 is marked by a point on housing.

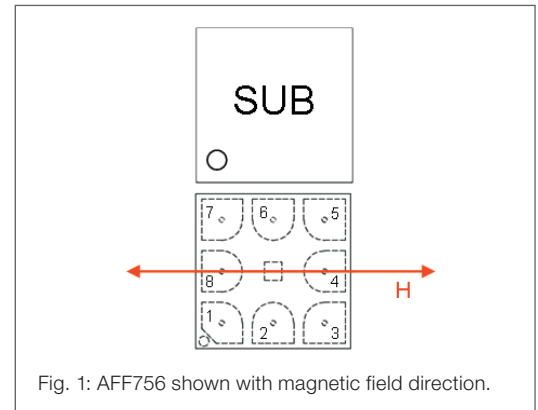


Fig. 1: AFF756 shown with magnetic field direction.

Marking

1st letter	Type of sensor	2nd letter	Calendar week	3rd letter	Year
S	AFF756	A	1 / 2	A	2009
		B	3 / 4	B	2010
	

Dimensions

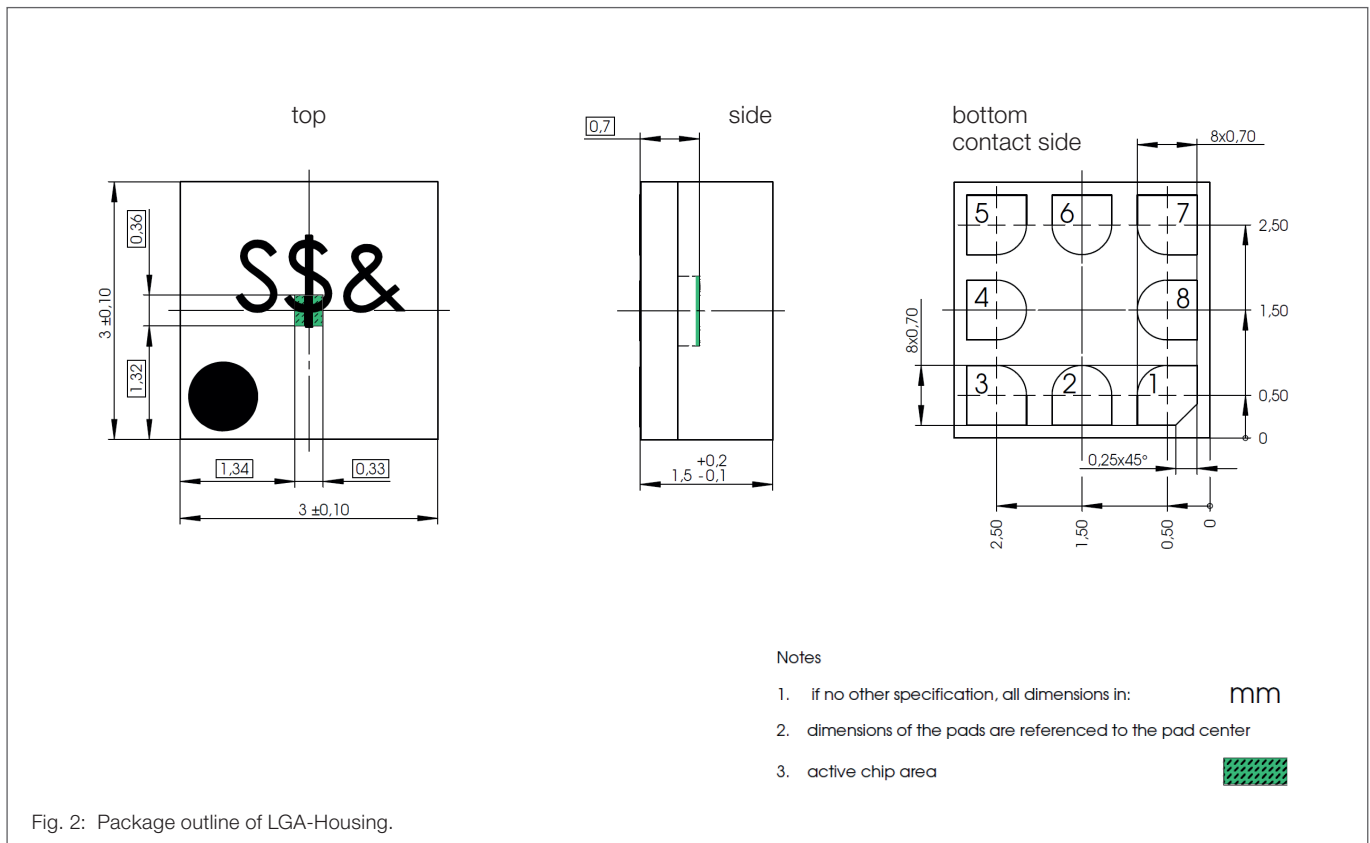


Fig. 2: Package outline of LGA-Housing.

General Information

Product Status

Article	Status
AFF756AMA-AE	The product is in series production.
Note	The status of the product may have changed since this data sheet was published. The latest information is available on the internet at www.sensitec.com .

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Changelist

Version	Description of the Change	Date
AFF765.DSE.10	Logo updated (pp. 1-5)	03/2024
AFF765.DSE00	Original (pp. 1-5)	06/2014

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