

AA746C

MagnetoResistive FreePitch Sensor

The AA746 is an angle sensor based on the Anisotropic MagnetoResistive (AMR) effect. The sensor contains two Wheatstone bridges with common ground (GND) and supply pin ($V_{\rm CO}$). They are shifted at a relative angle of 45° to one another.

A rotating magnetic field in the sensor plane delivers two sinusoidal output signals with the double frequency of the angle α between sensor and magnetic field direction shown in Fig. 1. The function of these signals is $\sin(2\alpha)$ and $\cos(2\alpha)$.

The AA746 is optimized for a low magnetic field strength down to 5 kA/m.



Product Overview

Article description	Package	Delivery Type
AA746CCA-AB	Die on wafer	Waferbox
AA746CMA-AE	LGA6L	Tape and Reel (2500)
AA746CHA-AE	SO8	Tape and Reel (4000)

Quick Reference Guide

Symbol	Parameter	Min.	Тур.	Max.	Unit
V _{CC}	Supply voltage	-	5.0	-	V
V _{off}	Offset voltage per V _{CC}	-2.0	-	+2.0	mV/V
V _{peak}	Signal amplitude per V _{CC}	10.5	11.5	12.5	mV/V
R _s	Sensor resistance	0.80	0.95	1.10	kΩ

Absolute Maximum Ratings

In accordance with the absolute maximum rating system (IEC60134).

Symbol	Parameter	Min.	Max.	Unit
V _{CC}	Supply voltage	-9.0	+9.0	V
T _{amb}	Ambient temperature	-40	+125	°C

Stresses beyond those listed under "Absolute maximum ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Features

- Based on the Anisotropic MagnetoResistive (AMR) effect
- Contains two Wheatstone bridges
- Sine and cosine output
- Temperature range from -40 °C to +125 °C

Advantages

- Non-contacting angle measurement
- Large air gap
- Excellent accuracy
- Position tolerant
- Minimal offset voltage
- Negligible hysteresis

Applications

- Incremental or absolute position measurement (linear and rotary motion)
- Motor commutation
- Rotational speed measurement
- Angle measurement (180° absolute on shaft end)





July 25th 2023

Data sheet

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Magnetic Data

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
H _{ext}	Magnetic field strength 1)		5.0	-	-	kA/m

The stimulating magnetic field in the sensor plane necessary to ensure the minimum error as specified in note 8.

Electrical Data

 $T_{amb} = 25$ °C; $H_{ext} = 25$ kA/m; $V_{CC} = 5$ V; unless otherwise specified.

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
V _{cc}	Supply voltage		-	5.0	-	V
V _{off}	Offset voltage per V _{cc}	See Fig. 1	-2.0	-	+2.0	mV/V
TC _{Voff}	Temperature coefficient of V _{off} ²⁾	T _{amb} = (-40+125)°C	-2.0	-	+2.0	(μV/V)/K
V _{peak}	Signal amplitude per V _{cc} ³⁾	See Fig. 1	10.5	11.5	12.5	mV/V
TC _{Vpeak}	Temperature coefficient of V _{peak} 4)	T _{amb} = (-40+125)°C	-0.36	-0.42	-0.48	%/K
R _s	Sensor resistance 5)		0.80	0.95	1.10	kΩ
R _B	Bridge resistance 6)		1.6	1.9	2.2	kΩ
TC _{RB}	Temperature coefficient of R _B 7)	T _{amb} = (-40+125)°C	0.22	0.26	0.30	%/K

²⁾
$$TC_{Voff} = \frac{V_{off(T2)} - V_{off(T1)}}{T_{2} - T_{1}}$$
 with $T_{1} = +25 \text{ °C}$; $T_{2} = +125 \text{ °C}$.

4)
$$TC_{Vpeak} = 100 \cdot \frac{V_{peak(T2)} - V_{peak(T1)}}{V_{oeak(T1)} \cdot (T_2 - T_1)}$$
 with $T_1 = +25$ °C; $T_2 = +125$ °C.

- ⁵⁾ Sensor resistance between pads 1 and 2 (bare die); pads 3 and 4 (LGA6L); pads 1/2 and 3/4 (SO8).
- ⁶⁾ Bridge resistance between pads 3 and 4; pads 5 and 6 (bare die); pads 1 and 5, pads 2 and 6 (LGA6L), pads 5 and 6, pads 7 and 8 (SO8).

$$7 \quad TC_{BB} = 100 \cdot \frac{R_{B(T2)} - R_{B(T1)}}{R_{B(T1)} \cdot (T_2 - T_1)} \quad \text{with } T_1 = +25 \, ^{\circ}\text{C}; \, T_2 = +125 \, ^{\circ}\text{C}.$$

Accuracy

 $T_{amb} = 25$ °C; $H_{ext} = 5$ kA/m; $V_{CC} = 5$ V; unless otherwise specified.

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
Δα	Angular error ⁸⁾		-	±0.25	±0.4	deg
Hyst	Angle hysteresis 9)		-	±0.20	±0.3	deg
k	Amplitude synchronism 10)		-0.5	0	+0.5	% of V _{peak}

- $\Delta \alpha = |x_{\text{real}} x_{\text{measured}}|$ without offset influences due to deviations from ideal sinusoidal characteristics.
- ⁹⁾ Angular difference between clockwise and counterclockwise rotation.

Angular difference between 0 angular difference between 0 has been 100 k = 100 - 100 ·
$$\frac{V_{peak1}}{V_{peak2}}$$
.

Dynamic Data

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
ω	Angular velocity of the magnetic field 11)		1	-	-	MHz

No significant amplitude attenuation.

 $^{^{3)}}$ Maximal output voltage without offset influences. Periodicity of V $_{\text{peak}}$ is $\sin(2\alpha)$ and $\cos(2\alpha)$.



General Data

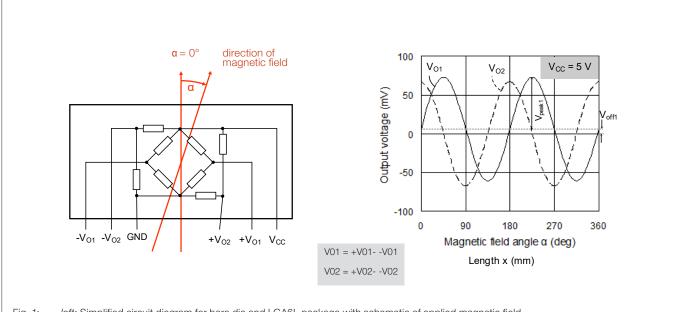
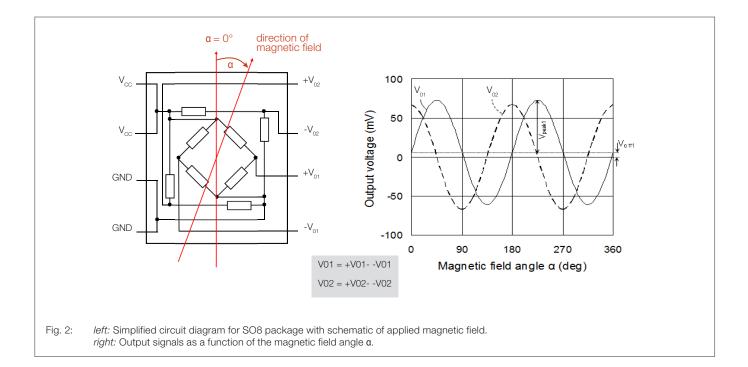
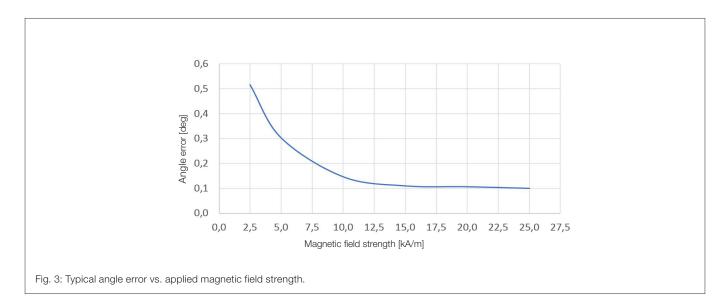


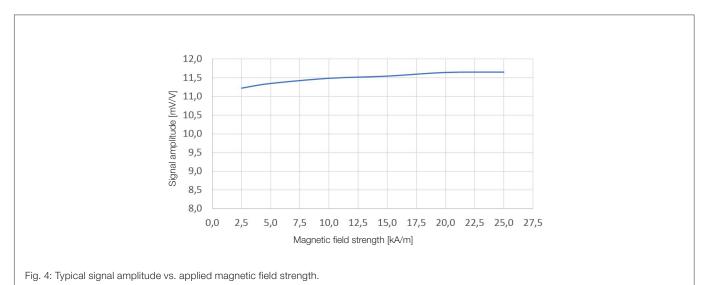
Fig. 1: *left:* Simplified circuit diagram for bare die and LGA6L package with schematic of applied magnetic field. *right:* Output signals as a function of the magnetic field angle α.

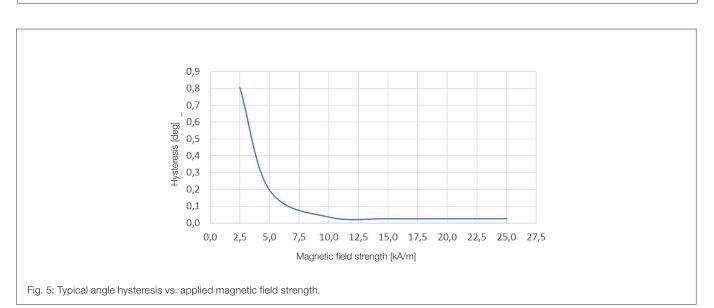




General Data





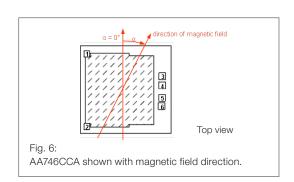




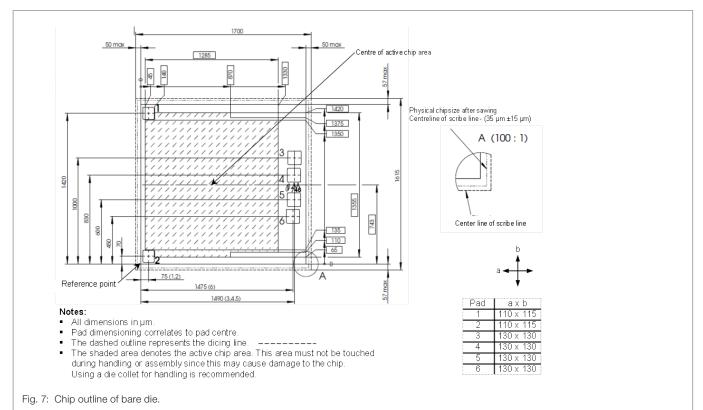
AA746CCA as Bare Die

Pinning

Symbol	Parameter
V _{cc}	Supply voltage
GND	Ground
+V ₀₂	Positive output voltage bridge 2
-V _{O2}	Negative output voltage bridge 2
+V _{O1}	Positive output voltage bridge 1
-V _{O1}	Negative output voltage bridge 1
	V _{CC} GND +V _{O2} -V _{O2} +V _{O1}



Dimensions



Data for Packaging and Interconnection Technologies

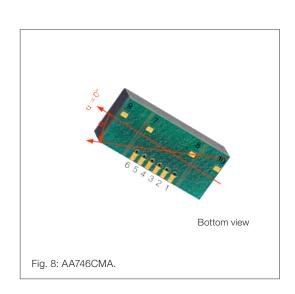
Parameter	Value	Unit
Chip area	1.7 x 1.6	mm
Chip thickness	254 ± 10	μm
Pad diameter (all)	See Fig. 7	μm
Pad thickness	0.8	μm
Pad material	AlCu	-



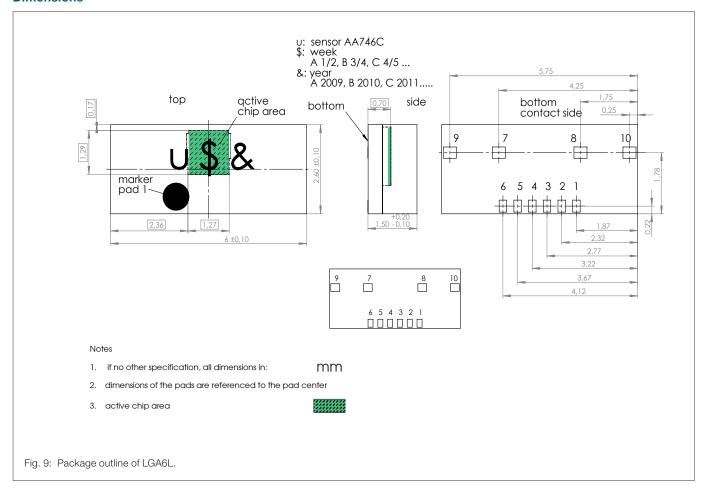
AA746CMA in LGA6L Housing

Pinning

9		
Pin	Symbol	Parameter
1	+V _{O1}	Positive output voltage bridge 1
2	+V _{O2}	Positive output voltage bridge 2
3	GND	Ground
4	V _{cc}	Supply voltage
5	-V _{O1}	Negative output voltage bridge 1
6	-V _{O2}	Negative output voltage bridge 2
7	n.c.	Not connected
8	n.c.	Not connected
9	n.c.	Not connected
10	n.c.	Not connected



Dimensions



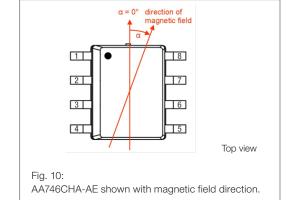
The moisture sensitivity level of the package is MSL2 according to JEDEC standard J-STD-020D. The allowable time period (floor life) after removal from a moisture barrier bag, dry storage or dry bake and before the solder reflow process is 1 year (\leq 30 °C / 60% RH).



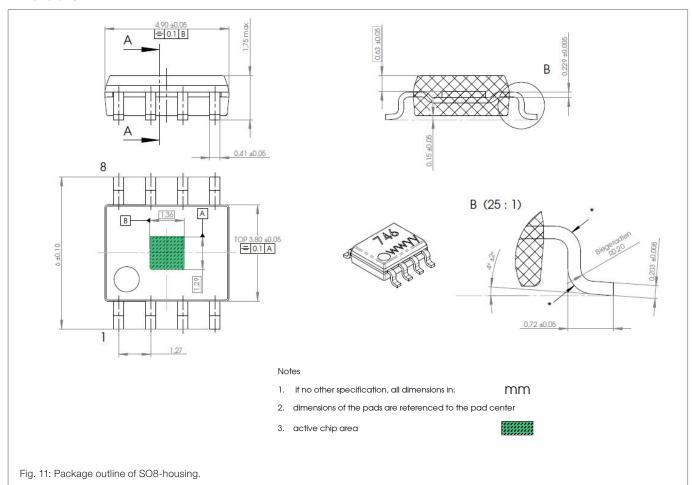
AA746CHA in SO8-housing

Pinning

9		
Pin	Symbol	Parameter
1	V _{cc}	Supply voltage 1)
2	V _{cc}	Supply voltage 1)
3	GND	Ground ²⁾
4	GND	Ground ²⁾
5	-V _{O1}	Output voltage bridge 1
6	+V _{O1}	Output voltage bridge 1
7	-V _{O2}	Output voltage bridge 2
8	+V _{O2}	Output voltage bridge 2



Dimensions



The moisture sensitivity level of the package is MSL2 according to JEDEC standard J-STD-020D. The allowable time period (floor life) after removal from a moisture barrier bag, dry storage or dry bake and before the solder reflow process is 1 year $(\le 30 \, ^{\circ}\text{C} / 60\% \, \text{RH})$.

Pin 1 and 2 are internally connected.

²⁾ Pin 3 and 4 are internally connected.



General Information

Product Status

Article	Status
AA746CCA-AB	The product is in series production.
AA746CMA-AE	The product is in series production.
AA746CHA-AE	The product is in series production.
Note	The status of the product may have changed since this data sheet was published. The latest information is available on the internet at www.sensitec.com.

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Changelist

Version	Description of the Change	Date
AA746C.DSE.03	Change of footnotes	07_2023
AA746C.DSE.02	Disclaimer supplement	06/2022
AA746C.DSE.01	Change of corporate design (pp. 1-8)	01/2022
AA746C.DSE.00	Original (pp. 1-9)	05/2019

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